

- CW**[*nn*] Moves the actuator in a clockwise direction, where *nn* = 1 to NP (see also **NP** command)
- Modes available: All (with restrictions – in two position modes, *nn* is not allowed)
- Examples** (multiposition, mode 3)
- Command: **CW**<enter>
Moves the actuator clockwise one position
- Command: **CW3**<enter>
Moves the actuator clockwise position 3
- Example** (two position, modes 1 and 2)
- Command: **CW**<Enter>
Moves the actuator from position B to position A. If the actuator is already in Position A, the command is ignored.
- DT**[*nnnn*] Sets a delay interval before the actuator automatically returns to its previous position, where *nnnn* = 0 – 65535 (milliseconds) (See also **TT** command)
- Modes available: Two position (1 and 2)
- Examples**
- Command: **DT**<enter>
Returns **DTnnnn** [0x0D] (*nnnn* = current delay setting)
- Command: **DT0**<enter>
Sets the delay time to 0 and disables the TT command
- Command: **DT1000**<enter>
Sets the delay timer to 1000 milliseconds (1 second)
- GO**[*nn*] Tells the actuator to go to position *nn*,
Where *nn* = 1 to NP (multiposition, mode 3)
= 'A' or 'B' (two position, modes 1 and 2)
(See also **NP** and **SM** commands)
- Modes available: All (see below)
- Examples** (two position, modes 1 and 2)
- Command: **GO**<enter>
Toggles the actuator to the other position
- Command: **GOB**<enter>
Moves the actuator from position A to position B
- Examples** (multiposition, mode 3)
- Command: **GO**<enter>
Advances the actuator to the next position
- Command: **GO3**<enter>
Moves the actuator to position 3 in the direction set by the SM command
- HM** Moves the actuator to position 1. If the actuator is already in position 1, the command is ignored.
- Modes available: Multiposition (3)
- Example**
- Command: **HM**<enter>
Moves the actuator from the current position to position 1