

- TO** Toggles the actuator to the opposite position from its current position; *i.e.*, if the actuator is currently in Position B, it will toggle to Position A.
- Modes available: Two position (1 and 2)
- Example**
 Command: **TO**<enter>
 Causes the actuator to toggle from one position to the other
- TT** Timed toggle: the actuator will toggle from its current position to the opposite, wait for a programmed amount of time, then toggle back to its original position.
 Note: This command is ignored if DT=0. (See also **DT** command)
- Modes available: Two position (1 and 2)
- Example**
 Command: **TT**<enter>
 The actuator will initiate the timed toggle procedure
- VR_n** Reports the current firmware version,
 where $n = [\text{null}]$ for the main PCB, or $n = 2$ for the serial interface PCB.
- Modes available: All
- Examples**
 Command: **VR**<enter>
 Returns: Current revision of the main PCB firmware
 Command: **VR2**<enter>
 Returns: Current revision of the serial PCB firmware
- /?** Displays the list of the primary commands for the actuator. The list is similar to the serial command table above but is not inclusive of all the commands.
- Modes available: All
- Example**
 Command: **/?**<enter>
 Returns: The list of commands for the actuator